TM AI COBOT





The future is here,

TM AI COBOT

Native AI engine + Robotic arm + Vision system

(All in ONE)









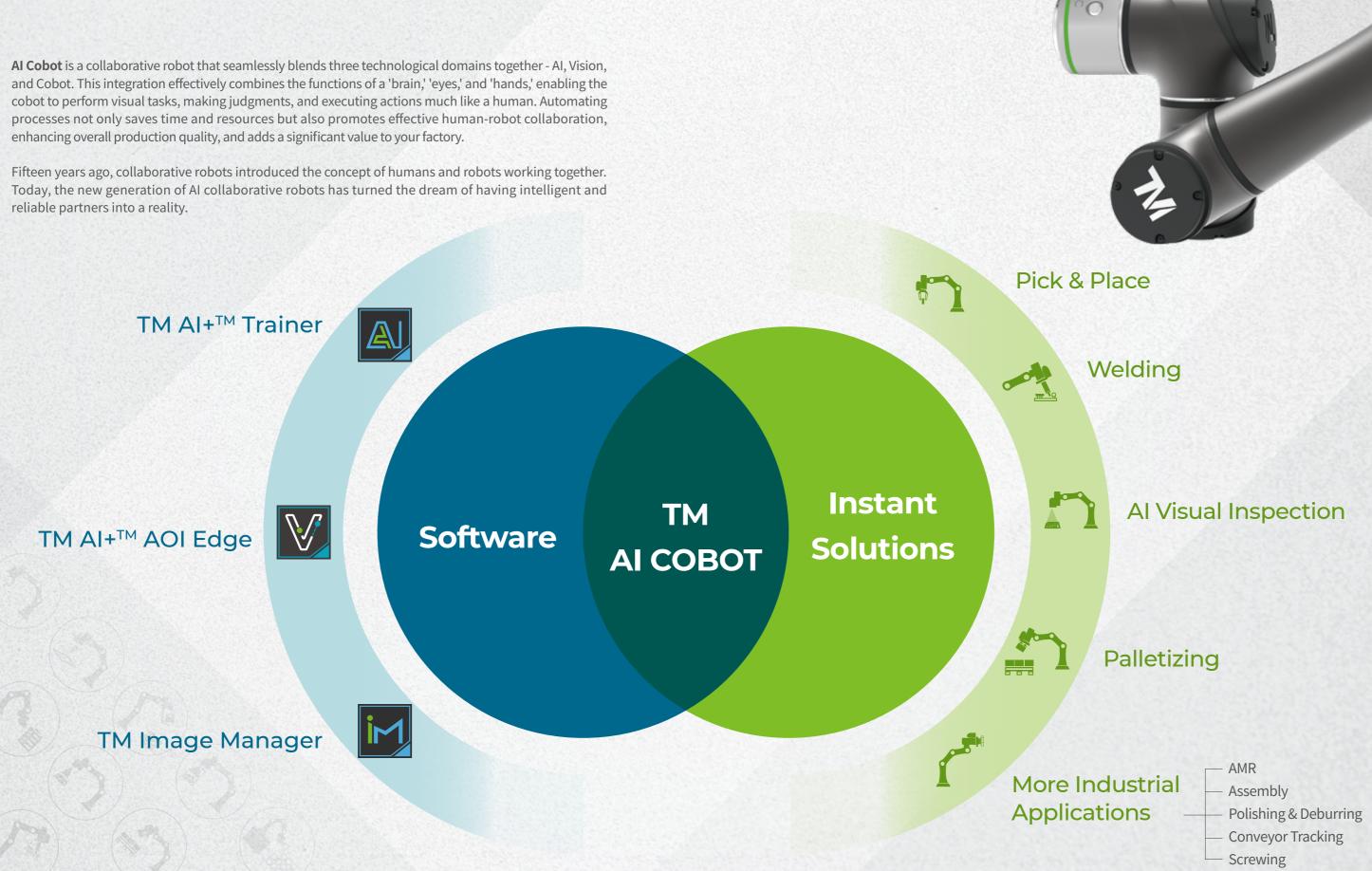








What Is An Al Cobot?



Industry Applications

TM AI Cobot offers exceptional performance and compatibility. Equipped with a built-in vision system, it enables the robot to perceive its surroundings. Its AI brain also translates image data into precise commands for tasks such as positioning and detection, seamlessly integrating with the robot arm to execute tasks efficiently.

In the era of AI, **TM AI Cobot** is the best choice to for realizing smart factories.

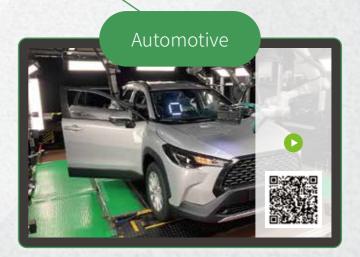












Introducing TM AI Cobot

The only AI-powered collaborative robot with advanced vision capabilities

TM AI Cobot

TM AI Cobot S Series



TM14**S**

1100 mm

917 mm

14 kg

TM20**S**

1300 mm

1300 mm

20 kg

TM AI Cobot Series

TM5**S**

946 mm

746 mm

Reach

5 kg

Payload |

Reach |

TM6S

1800 mm

946 mm

6 kg



TM12**S**

1300 mm

1100 mm

12 kg

TM7S

758 mm

7 kg

1300 mm

+ Additional Types

TM Mobile Series

TM25**S**

1902 mm

30 kg*

TM Mobile Series cobots can be integrated with almost all AGV/AMR brands on the market. With its embedded vision and TM Landmark vision function, the mobile series is extremely suitable for applications and tasks that require mobility. Such as machine tending or palletizing.

TM30**S**

1702 mm

35 kg*

No Built-in Vision Robot Series

TM Robot Series offers robot arms with no built-in vision for users who want to integrate external cameras by themselves. Feel free to check on the pre-verified list of cameras from our TM Plug&Play™ series to save time on finding a compatible camera.

*Under the palletizing scenario

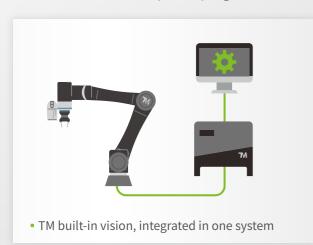
Introducing TM AI Cobot

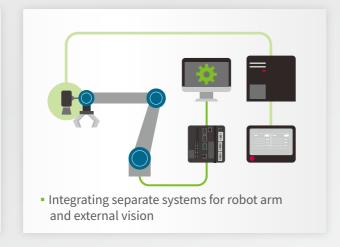
The only AI-powered collaborative robot with advanced vision capabilities

SMART

A perfect integration of cobot and machine vision

- Hand and eye integration for time/labor-saving solution
- Powerful vision function: The combination of traditional machine vision and AI vision offers the user a comprehensive vision function including vision positioning, measurement, defect inspection, OCR and barcode reading
- Easily manage both robot arm and vision functions within a single software, eliminating the need to learn two separate programs and concerns about system compatibility or interface issues





	TM built-in vision	Robot arm + External vision
Camera	All-in-one	Requires additional mechanism for integration
Camera signal cable and power cord	Internally routed cables	Externally routed cables can lead to problems like tangled or pulled cables or dust resulted from friction
Vision recognition system	5M color camera, auto focus, built-in light source, various applications	Complicated configuration of lens, camera, light source and software
Vision and Robot Programming	Integrated in one software TMflow™ for easy programming	Need to handle the communication interface of 2 different software
Charge	The cost of the robot arm includes the vision system	Additional charge of vision software /hardware is required

A plug-and-play 3D vision solution requires no additional software/hardware integration

When incoming materials are stacked or arranged in different configurations, the positioning function may become ineffective or less accurate due to the limitations of a standard robot's 2D vision, which cannot capture 3D coordinates. To overcome this challenge, Techman Robot has introduced TM 3D Vision™, a 3D machine vision solution with paried designated Plug&Play 3D camera, designed to expand the range of items recognizable by the vision system and enhance the precision of both vision-based positioning and arm movement.





Traditional Solution

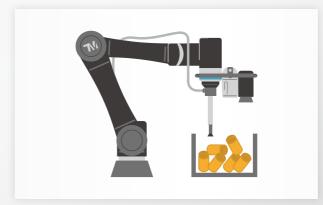
Requires more time and labor costs to integrate robot arm, 3D camera, and software from different brands

All-In-one Solution

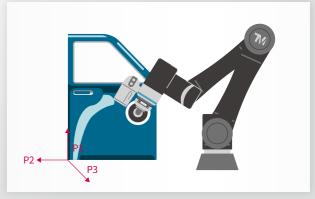
Significantly reduces integration costs and efforts, maintenance and accountability issues

Features

- The integration of 3D software and TMflow™ interface achieves high integration and easy operation
- No additional vision controller is required. No need for complicated system handshaking settings
- Can be used with the collision check function and prevent any potential collision risks.
 This is highly recommended for the Random Bin Picking applications.



Picking up scattered materials



Single item 3D positioning

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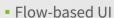
SIMPLE

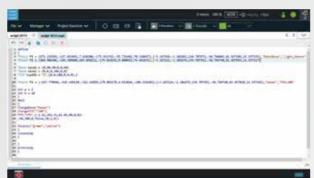
More Freedom to Program the Cobot

TMflow™ is a user-friendly software that allows you to create and edit robot tasks through a graphical interface using a series of function nodes, making it easy for first-time users to learn our flow-based programming without any robotics experience.

If you prefer non-graphical programming, experience a more flexible way to program by using the new Script Node and Script Project. The Script feature allows experienced engineers to program with complex logic, and freely edit robot tasks by compiling codes. Embrace the method that suits you best and enjoy coding with unparalleled freedom!







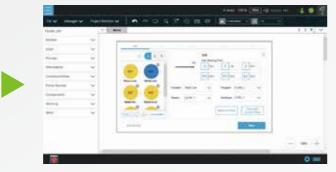
Script for Complex Logical Programming

Create Personalized Interface with TMcraft for 2nd Development

TMcraft is a new architecture that allows you to create your own customized UI or background program and embed it onto TMflow™, our cobot programming software. It offers the freedom to develop third-party plug-and-play applications using C# and WPF development. Additionally, a wizard is available to facilitate the development of high-level applications, such as welding, palletizing, and sanding, making it easier to customize and create the applications you need.

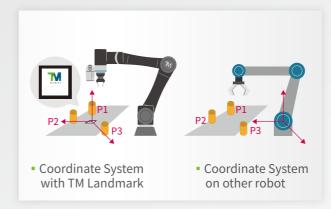


 Developers can develop nodes in their own environment



• Embed into TMflow™ using third-party plugins

Built-in vision with one-click positioning



TM Landmark

General robot has the coordinate system built on its base, when the relative position between the objects and the robot changes, the robot require re-adjustment. With TM Landmark, the coordinate system is built on the landmark, the robot will only need to scan the landmark and the coordinate info can be updated without re-adjustment. This is especially recommended to robot with AGV!



Visual Calibration

TM Calibration board can largely reduce the complexity of visual calibration process. Whether users are using EIH, ETH or Upward-looking camera, just simply place the calibration board under the camera, press the button and TMvision™ will do all the work!

Built-in vision application











Eye-in-Hand

Eye-to-Hand Upward-looking Conveyor Tracking





Barcode/ QR code Reading









Distance and Angle

Measurement



Caliper



Count (Edge)





Image Classification

Object Detection





Semantic Segmentation



Anomaly Detection

Segmentation

AI Vision Software

Powering the future of factories with AI power



Completely integrate hands, eyes and brain in automation field

TM AI+™ Trainer is a software tool that will help you manage image data, set up AI training parameters, and train AI models. The AI solution can help you train a model that fits your needs effortlessly. This AI model can be applied to both the robot arm and machine vision, thus forming a powerful combination of the arm(cobot), eye(machine vision), and brain(AI). Easy and simple UI helps the user to rapidly and conveniently introduce AI vision technology to production. Al incorporating vision system can effectively eliminate quality issues resulted from fatigue or human error.

Features

- A graphical interface that is easy to learn
- Designed as a browser-based software that you can log in anywhere with a web browser
- All image data used for AI model training is stored in a local database to ensure enterprise classified data is secure
- Powerful AI Vision technology with capabilities including anomaly detection, classification, object detection, and semantic segmentation

4 steps for easy AI model training

Image collection





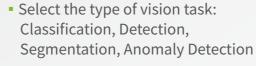
Collect Image Data

 Take multiple photos of the object and upload them to TM AI+™ Trainer

Annotation



TM AI+™ Trainer



- Label the uploaded image samples
- Configure training parameters and begin training
- Evaluate the training outcome

Training



Deployment

Import AI model

- Download the trained AI model from the TM AI+™ Trainer to TM Robot or external camera
- Begin Al inference

TM Image Manager

Comprehensive quality traceability for your product

After an enterprise sells its product to customers, they often must deal with customer feedback or complaints. Therefore, companies need to establish a comprehensive quality traceability system.

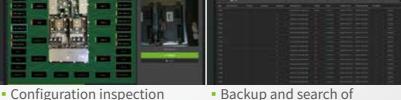
TM Image Manager is a software tool that is highly compatible with the vision function of TM AI Cobot. It can help you effectively manage the quality inspection records of each product.

The inspector can monitor the inspection progress in real time and the results are automatically recorded as image data. This data can be reviewed at any time to increase inspection accuracy. Furthermore, a quality resume can be improved and the potential cost of after-sales service activities can be reduced.

Features

- Browser-based interface for intuitive and easy operation
- Manage inspection images and results through the database to address the needs of backup and search
- The user can filter the images of quality inspection by different conditions, like time, work order, barcode, etc. at any time
- Help inspectors to compare the images of inspection and standard item to effectively reduce the probability of misjudgement
- The user can plan and design inspection configuration to perform real-time monitoring on inspection position, result and progress







and progress review

inspection history

 Support human double-check interface

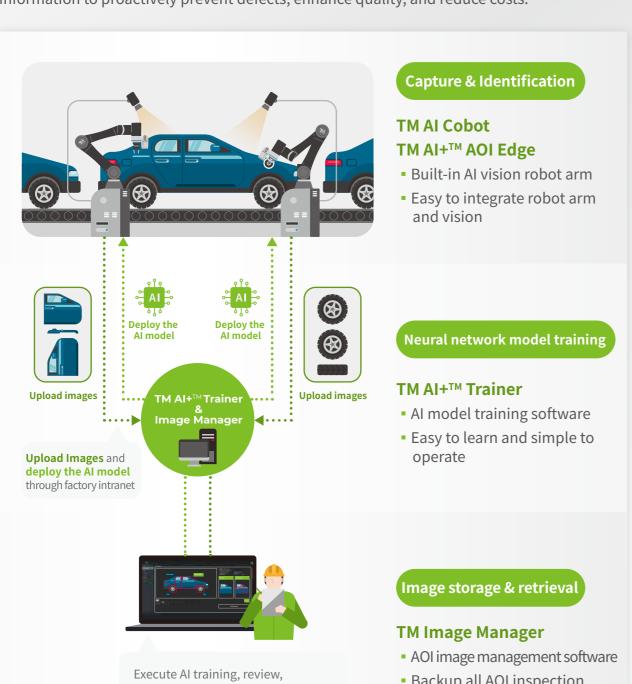


Al Vision Software

Powering the future of factories with Al power

AI Vision Operating Architecture

The graphical interface of TM AI Cobot's integrated vision system eliminates the need for programming and enables a seamless process from image collection and annotation to training and deployment. It serves as an ideal solution for small and medium-sized enterprises (SMEs) lacking an AI or software division. Throughout production, AI Cobot accumulates valuable production history data, empowering companies to track, analyze, and integrate this information to proactively prevent defects, enhance quality, and reduce costs.



Application Examples

Assembly Inspection





 Checking if the tires are wrapped with PE film



 Checking if all wires are connected correctly



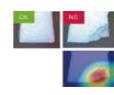


 Sorting different materials for wooden furniture



 Recognition of pizza flavor and crust





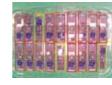
 Identifying objects with damage on the edge



 Checking if there are metal scrap on the surface



AI OCR



 Counting the amount of the object in the tray



Objects detection and 3D positioning

Execute AI training, review, and image retrieval through browser

 Backup all AOI inspection images and establish product traceability



Checking scratches on DRAM gold fingers



 Checking the dents on metal parts



Label text reading



Label text reading

TM Plug&Play™ Solution

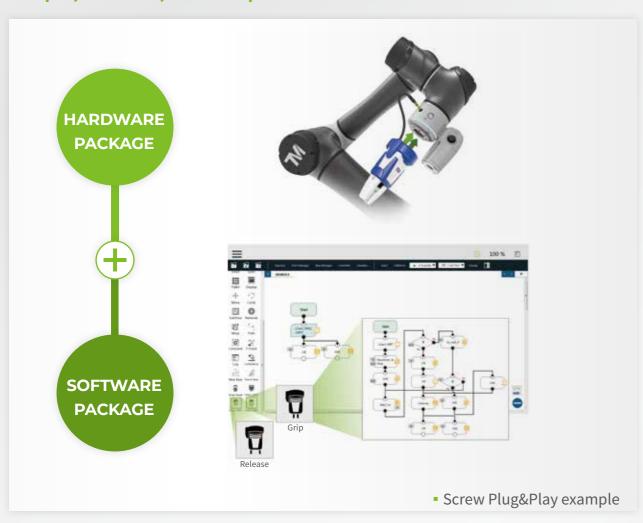
TM certified, perfect integration, and usable upon installation

TM AI Cobot works with peripheral equipment vendors to create a comprehensive TM Plug&Play™ ecosystem. Each certified TM Plug&Play™ product has been calibrated and tested by Techman Robot and peripheral equipment vendors. This ensures users benefit from an optimal experience and highly reliable robot performance, while significantly reducing the time and labor costs associated with hardware production and automation programming.

Start to use within 5 minutes



Simple, efficient, and fast production line introduction



TMPlug&Play[▶]

CERTIFIED



Advantech AIR-3002022 -TM AI+ Trainer



FlexiBowl® Kit for TM



ARH350A Kit for TM



9105-TM-Axia80



Industrial Camera



RCKL/RHLF/RLSH -TM Gripper



COBOTRACKS Linear Motion Plug&Play for TM



DH-Robotics Adaptive Gripper DH-3 TM Kit



FWFITIX LIFTKIT-TM Contact Flange-Kit



Industrial Camera



KIT-TM-J



HIWIN Electric Gripper X-series



Ensenso N36/N46



3D e-chain TM Kit - PMA Tubes Screw Driver Solution



ACF-K Active

All-in-One Gripper for TM Robot (3-Finger)



Murrplastik Murrplastik FHS-SH-Set



NABELL



NITTOSEIKO Pick and Drive System PD400TM





KII FWS





Pickit3D Vision Solution



RoboDK Simulation and Offline Programming Software



FTS-300-TM-KIT



Adaptive Gripper 2-Finger 85/140 TM Kit



FXCB



Changing by SCHUNK - Plug & Work Portfolio Techman Robot



Collaborative gripping EGP-C



Magnet Gripper Unit for Collaborative Robots



CHY2B-S80



GRIPKIT-CR-PRO-L



HRC-03 TM-Kit

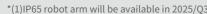


71 ÍN ROBOTICS Universal Mobile Stand



TM AI Cobot S Series Specification

						Specif	ication							
Мо	odel	TM5S	TM6S	TM7S	TM12S	TM5S-M	TM6S-M	TM7S-M	TM12S-M	TM5S-X	TM6S-X	TM7S-X	TM12S-X	
We	Weight		35.5kg	22.9kg	33.3kg	23.9kg	35.5kg	22.9kg	33.3kg	23.6kg	35.2kg	22.6kg	33kg	
Maximur	m Payload	5kg	6kg	7kg	12kg	5kg	6kg	7kg	12kg	5kg	6kg	7kg	12kg	
Re	each	946mm	1800mm	758mm	1300mm	946mm	1800mm	758mm	1300mm	946mm	1800mm	758mm	1300mm	
Joint Ranges	J1, J2, J4, J5, J6	+/- 360°												
Runges	J3	+/- 158°	+/- 166°	+/- 152°	+/- 162°	+/- 158°	+/- 166°	+/- 152°	+/- 162°	+/- 158°	+/- 166°	+/- 152°	+/- 162°	
	J1	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	
	J2	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	210°/s	130°/s	
Speed	J3	210°/s												
opeca	J4	225°/s												
	J5	225°/s												
	J6						450)°/s						
	Speed							5m/s						
	atability	+/- 0.03mm	+/- 0.10mm	+/- 0.03mm	+/- 0.03mm	+/- 0.03mm	+/- 0.10mm	+/- 0.03mm	+/- 0.03mm	+/- 0.03mm	+/- 0.10mm	+/- 0.03mm	+/- 0.03mm	
Degree O	of Freedom							ng joints						
	Control Box						igital In: 16 /	0						
I/O							Analog In: 2 /							
-, -	Tool Conn.		Digital In: 3 / Digital Out: 3											
		DO_0 (DO-0/AI) / DO_1 (DO-1/RS485-) / DO_2 (DO-2/RS485+)												
I/O Pow	er Supply	24V 2.0A for control box, 24V 1.5A for tool												
IP Class	sification	IP65 (Robot Arm) * ⁽¹⁾ IP65 (Robot Arm) * ⁽¹⁾ IP54 (Control Box)							IP65 (Robot Arm) * ⁽¹⁾ IP54 (Control Box)					
	al Power Imption	240 W	400 W	240 W	400 W	240 W	400 W	240 W	400 W	240 W	400 W	240 W	400 W	
Temp	erature						0~5	i0°C						
Clear	nliness						ISO C	lass 3						
Power	r Supply	100~240 VAC, 50~60 Hz 24~60 VDC									100~240 VA	C, 50~60 Hz		
I/O In	iterface	2×COM, 1×HDMI, 3×LAN, 2×USB2.0, 4×USB3.0												
Commi	unication	RS-232/RS-422/RS-485, Ethernet, Modbus TCP/RTU (master & slave)												
Commi	unication	Optionally support specified network card of PROFINET, EtherNet/IP, EtherCAT, CC-Link *(2)												
	amming onment	TMflow (flowchart based), TMscript (script based), TMcraft (developer based)												
		TÜV certificated ISO 13849-1, ISO 10218-1, ISO/TS 15066												
Certif	fication	SGS certificated UL1740, CAN/CSA Z424-14 (R2019)												
		CE, NSF/ANSI 169 (optional), SEMI S2 (optional)												
						AI & Rob	ot Vision							
AI Fu	ınction	(Classification	n, Object Det	ection, Segn	nentation, A	nomaly Dete	ction, AI OCF	2					
Appli	ication	Positioning, 1D/2D Barcode Reading, OCR, Defect Detection, Measurement, Assembly Check							N/A					
Dogition	a a A a a	2D Positioning: 0.1 mm												
Positionin	ng Accuracy	TM Landmark 3D Positioning (Working Point away from Landmark 100/200/300 mm): 0.10/ 0.20/ 0.33 mm * ⁽³⁾												
Eye in Har	nd (Built in)	Au	uto-focused	color camera	with 5M res	olution, Wo	rking distanc	e 100 mm ~	∞					
	nd (Optional)			Sup	oort Maximu	m 2× GigE 2	D cameras o	r 1× GigE 2	D Camera + 1	× 3D Came	ra * ⁽⁴⁾			



^{*(1)}IP65 robot arm will be available in 2025/Q3
*(2)Please contact sales/agent for detailed specifications.



					Specif	ication						
TM14S	TM20S	TM25S	TM30S	TM14S-M	TM20S-M	TM25S-M	TM30S-M	TM14S-X	TM20S-X	TM25S-X	TM30S-X	
33kg	33.3 kg	81.6kg	80.6kg	33kg	33.3 kg	81.6kg	80.6kg	32.7kg	33 kg	81.3kg	80.3kg	
14kg	20kg	25kg	30kg	14kg	20kg	25kg	30kg	14kg	20kg	25kg	30kg	
1100mm	1300mm	1902mm	1702mm	1100mm	1300mm	1902mm	1702mm	1100mm	1300mm	1902mm	1702mm	
					+/- 360	0						
+/- 159°	+/- 162°	+/- 166°	+/- 170°	+/- 159°	+/- 162°	+/- 166°	+/- 170°	+/- 159°	+/- 162°	+/- 166°	+/- 170°	
130	0°/s	100	0°/s	13	0°/s	10	0°/s	130	0°/s	100	0°/s	
130°/s	95°/s	100	0°/s	130°/s	95°/s	10	0°/s	130°/s	95°/s	100	0°/s	
210°/s	125°/s	130	0°/s	210°/s	125°/s	13	0°/s	210°/s	125°/s	130	0°/s	
225°/s	160°/s	195	5°/s	225°/s	160°/s	19	5°/s	225°/s	160°/s	19	5°/s	
225°/s	190°/s	210	0°/s	225°/s	190°/s	21	0°/s	225°/s	190°/s	210	0°/s	
45	0°/s	225	5°/s	45	0°/s	22	5°/s	450	0°/s	225°/s		
4.	5m/s	5.2	2m/s	4.	5m/s	5.2	2m/s	4.5	5m/s	5.2	2m/s	
+/- 0.03mm	+/- 0.05mm	+/- 0	.05mm	+/- 0.03mm	+/- 0.05mm	<u>. </u>	.05mm	+/- 0.03mm	+/- 0.05 mm	+/- 0	.05mm	
						ng joints						
						Digital Out: 16						
						Analog Out: 2						
						Digital Out: 3						
					/ DO_1 (DO-1/		, ,	+)				
				24V 2.	.0A for control	•	or tool					
	•	ot Arm) * ⁽¹⁾			IP65 (Rob	oot Arm) * ⁽¹⁾		IP65 (Robot Arm) * ⁽¹⁾ IP54 (Control Box)				
	IP54 (Cor	ntrol Box)							IP54 (Cor	ntrol Box)		
400 W 600 W				400 W 600 W		0 W	400 W		60	0 W		
		l			0~!	50°C						
					ISO C	Class 3						
							100~240 VA	C, 50~60 Hz	200~240 VA	C, 50~60 Hz		
2×COM, 1×HDMI, 3×LAN, 2×USB3.0												
			RS-2	32/RS-422/RS-	485, Ethernet,	Modbus TCP/F	RTU (master & :	slave)				
		0	ptionally supp	ort specified n	etwork card of	PROFINET, Eth	nerNet/IP, Ethe	erCAT, CC-Link	*(2)			
			TMflow (f	lowchart base	d), TMscript (so	cript based), TI	Mcraft (develo	per based)				
				TÜV certifica	ted ISO 13849-	1, ISO 10218-1,	ISO/TS 15066					
				SGS certifi	cated UL1740,	CAN/CSA Z424	-14 (R2019)					
				CE, NSF/	ANSI 169 (optio	onal), SEMI S2	(optional)					
					AI & Rob	ot Vision						
	Classific	ation, Object D	etection, Segr	mentation, And	omaly Detectio	n, Al OCR						
	Positioning, 1D/2D Barcode Reading, OCR,								h.i	/^		
		Defect Detection, Measurement, Assembly Check								/A		
								1				
TM Landm	ark 3D Position		2D Position	ing: 0.1 mm		n)· 0 10/ 0 20/	0 33 mm * ⁽³⁾					

^{*(1)}IP65 robot arm will be available in 2025/Q3

Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera *(4)

^{*(3)}The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

^{*(4)}Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

^{*(2)}Please contact sales/agent for detailed specifications.

^{*(3)}The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

^{*(4)}Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

TM AI Cobot Specification

			Specificati	on							
N	1odel	TM5-700	TM5-900	TM5M-700	TM5M-900	TM5X-700	TM5X-900				
Weight		22.1kg	22.6kg	22.1kg	22.6kg	21.8kg	22.3kg				
Maximum Payload		6kg	4kg	6kg	4kg	6kg	4kg				
R	Reach	746mm	946mm	746mm	946mm	746mm	946mm				
	J1,J6	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°				
Joint Ranges	J2,J4,J5	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 360°	+/- 360°				
	J3			+/- 155°		•					
	J1,J2	180°/s									
	J3	180°/s									
Speed	J4	225°/s									
	J5			225°/s							
	J6			225°/s							
Max	c. Speed			4m/s							
Repe	eatability			+/- 0.05mm	1						
Degree	Of Freedom			6 rotating join	nts						
	Control Box			Digital In: 16 / Digita	al Out: 16						
I/O	Controt box	Analog In: 2 / Analog Out: 1									
1/0	Tool Conn.	Digital In: 4 / Digital Out: 4									
	Tool Colli.	Analog In: 1 / Analog Out: 0									
I/O Pov	wer Supply	24V 2.0A for control box, 24V 1.5A for tool									
ID Clas	ssification	IP54 (Robot Arm)									
IP Clas	SSIIICation	IP32 (Control Box)									
Typical Pow	er Consumption	220 W									
Tem	perature	0-50°C									
Clea	anliness	ISO Class 3									
Powe	er Supply	100-240 VA	100-240 VA	C, 50-60 Hz							
I/O I	nterface	3×COM, 1×HDMI, 3×LAN, 4×USB2.0, 2×USB3.0									
Comm	nunication	RS-232, Ethernet, Modbus TCP/RTU (master & slave)									
Collin	lunication	Optionally support specified network card of PROFINET, EtherNet/IP, EtherCAT, CC-Link *(1)									
Programmi	ng Environment	TMflow (flowchart/script based)									
Cort	ification	ISO 13849-1, ISP 10218-1, ISO/TS 15066									
Cert	ilication	CE, SEMI S2 (optional)									
			AI & Robot Vi	sion							
AI F	Al Function		Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR								
Арр	Application		Positioning, 1D/2D Barcode Reading, OCR, Defect Detection, Measurement, Assembly Check								
		2D Positioning: 0.1 mm * ⁽²⁾									
Position	ing Accuracy	TM Landmark 3D Positioning (Working Point away from Landmark 100/200/300 mm): 0.24/0.53/1.00 mm * ⁽²⁾									
Eye in Ha	and (Built in)	Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞									
	nd (Optional)			GigE 2D cameras or 1×		3D Camera *(3)					



									- 1			
Specification												
TM12	TM14	TM16	TM20	TM12M	TM14M	TM16M	TM20M	TM12X	TM14X	TM16X	TM20X	
32.8kg	32.5kg	32kg	32.8kg	32.8kg	32.5kg	32kg	32.8kg	32.5kg	32.2kg	31.7kg	32.5kg	
12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg	
1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mm	
+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°	+/- 360°	+/- 360°	
+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 360°	+/- 360°	+/- 360°	+/- 360°	
+/- 166°	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163°	+/- 155°	+/- 166°	
120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s	
180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s	
180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	
180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s	
180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s	
						n/s						
						.1mm						
					6 rotatii	ng joints						
					Digital In: 16 /	Digital Out: 16	j					
					Analog In: 2/	Analog Out: 1						
					Digital In: 4/	Digital Out: 4						
					Analog In: 1/	Analog Out: 0						
				24V 2.	0A for control	box, 24V 1.5A f	or tool					
					IP54 (Ro	,						
					IP32 (Cor	ntrol Box)						
					300	O W						
					0-5	0°C						
					ISO C	lass 3						
	100-240 VA	C, 50-60 Hz			22-60 VDC		24-60 VDC	100-240 VAC, 50-60 Hz				
				3×COM,1	×HDMI,3×LA	N, 4×USB2.0,	2×USB3.0					
				RS-232, Eth	ernet, Modbus	TCP/RTU (ma	ster & slave)					
		Ol	ptionally supp	ort specified n	etwork card of	PROFINET, Eth	nerNet/IP, Ethe	erCAT, CC-Link	*(1)			
				Т	Mflow (flowcha	art/script base	d)					
				ISO 1	.3849-1, ISP 10	218-1, ISO/TS	15066					
					CE, SEMI S	2 (optional)						
					AI & Rob	ot Vision						
	Classific	ation, Object D	etection, Segr	mentation, And	omaly Detectio	n, AI OCR						
	Positioning, 1D/2D Barcode Reading, OCR,											
Defect Detection, Measurement, Assembly Check									/A			
2D Positioning: 0.1 mm * ⁽²⁾												
	(Working		TM Landmark m Landmark 1		g n): 0.24/0.53/1	.00 mm *(2)						
					ing distance 10							
				,	3			1				

Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera *(3)

^{*(1)}Please contact sales/agent for detailed specifications.

*(2)The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

*(3)Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

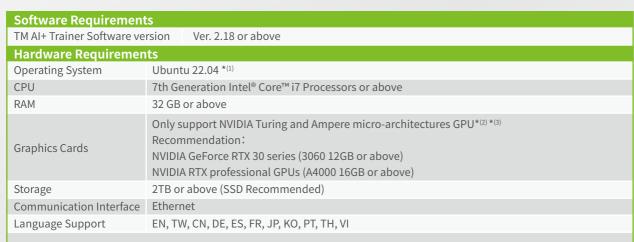
^{*(1)}Please contact sales/agent for detailed specifications.

*(2)The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.

*(3)Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.

Software Specification





- *(1) TM AI+ Trainer cannot be installed in a virtual environment on a personal computer, such as VirtualBox.
- *(2) Only NVIDIA GPUs are supported; GPUs from other manufacturers like AMD and Intel are not compatible.
- *(3) NVIDIA GPUs based on other micro-architectures, such as the GeForce RTX 40 series (Ada Lovelace architecture), are also not supported.

TM Image Manager Installation Requirements



Software Requirement	ts						
TMflow Software Version	Ver. 2.18 or above						
Hardware Requiremen	its						
Operating System	Ubuntu 22.04 *(1) *(2)						
CPU	Gen 7 intel i7 or above						
RAM	32 GB or above						
Storage	SSD 2TB-8TB						
Communication Interface	Ethernet						
Language Support	EN, TW, CN, JP, KO, TH						
Remark	Supports up to 10 TM AI Cobots and AI+ AOI Edges for continuous, simultaneous image transmissi						

- *(1) Image Manager is not allowed to be installed on the virtual environment of personal computer, like VirtualBox.
- *(2) Please verify if the computer hardware supports Ubuntu 22.04 LTS 64.
- *(3) When more than 10 connections are established with simultaneous image transmissions, users should assess the potential risks of system overload.

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