

A close-up photograph of a robotic joint, likely a gripper or end effector, featuring a grey sensor module mounted on a black and silver mechanical arm. The background is a solid green color.

Specification											
TM14S	TM20S	TM25S	TM30S	TM14S-M	TM20S-M	TM25S-M	TM30S-M	TM14S-X	TM20S-X	TM25S-X	TM30S-X
33kg	33.3 kg	82.1kg	81.1kg	33kg	33.3 kg	82.1kg	81.1kg	32.7kg	33 kg	81.8kg	80.8kg
14kg	20kg	25kg	30kg	14kg	20kg	25kg	30kg	14kg	20kg	25kg	30kg
1100mm	1300mm	1902mm	1702mm	1100mm	1300mm	1902mm	1702mm	1100mm	1300mm	1902mm	1702mm
+/- 360°											
+/- 159°	+/- 162°	+/- 166°	+/- 170°	+/- 159°	+/- 162°	+/- 166°	+/- 170°	+/- 159°	+/- 162°	+/- 166°	+/- 170°
130°/s	130°/s	100°/s		130°/s	130°/s	100°/s		130°/s	130°/s	100°/s	
130°/s	95°/s	100°/s		130°/s	95°/s	100°/s		130°/s	95°/s	100°/s	
210°/s	125°/s	130°/s		210°/s	125°/s	130°/s		210°/s	125°/s	130°/s	
225°/s	160°/s	195°/s		225°/s	160°/s	195°/s		225°/s	160°/s	195°/s	
225°/s	190°/s	210°/s		225°/s	190°/s	210°/s		225°/s	190°/s	210°/s	
450°/s	225°/s	225°/s		450°/s	225°/s	225°/s		450°/s	225°/s	225°/s	
4.5m/s	4.5m/s	5.2m/s		4.5m/s	4.5m/s	5.2m/s		4.5m/s	4.5m/s	5.2m/s	
+/- 0.03mm	+/- 0.05mm	+/- 0.05mm		+/- 0.03mm	+/- 0.05mm	+/- 0.05mm		+/- 0.03mm	+/- 0.05 mm	+/- 0.05mm	
6 rotating joints											
13.5kg		16.3kg		8.9kg		11.7kg		13.5kg		16.3kg	
Digital In: 16 / Digital Out: 16											
Analog In: 2 / Analog Out: 2											
Digital In: 3 / Digital Out: 3											
DO_0 (DO-0/AI) / DO_1 (DO-1/RS485-) / DO_2 (DO-2/RS485+)											
24V 2.0A for control box, 24V 1.5A for tool											
IP65 (Robot Arm) IP54 (Control Box)				IP65 (Robot Arm)				IP65 (Robot Arm) IP54 (Control Box)			
400 W		580 W		400 W		580 W		400 W		580 W	
0~50°C											
ISO Class 3											
100~240 VAC, 50~60 Hz		200~240 VAC, 50~60 Hz		24~60 VDC		48~60 VDC		100~240 VAC, 50~60 Hz		200~240 VAC, 50~60 Hz	
2×COM, 1×HDMI, 3×LAN, 2×USB2.0, 4×USB3.0											
RS-232/RS-422/RS-485, Ethernet, Modbus TCP/RTU (master & slave)											
Optionally support specified network card of PROFINET, EtherNet/IP, EtherCAT, CC-Link ^{*(1)}											
TMflow (flowchart based), TMscript (script based), TMcraft (developer based)											
TÜV certificated ISO 13849-1, ISO 10218-1, ISO/TS 15066											
SGS certificated UL1740, CAN/CSA Z424-14 (R2019)											
CE, NSF/ANSI 169 (optional), SEMI S2 (optional)		CE, SEMI S2 (optional)		CE, NSF/ANSI 169 (optional), SEMI S2 (optional)		CE, SEMI S2 (optional)		CE, NSF/ANSI 169 (optional), SEMI S2 (optional)		CE, SEMI S2 (optional)	
AI & Robot Vision											
Classification, Object Detection, Segmentation, Anomaly Detection, AI OCR								N/A			
Positioning, 1D/2D Barcode Reading, OCR, Defect Detection, Measurement, Assembly Check											
2D Positioning: 0.1 mm ^{*(2)}											
TM Landmark 3D Positioning (Working Point away from Landmark 100/200/300 mm): 0.10/ 0.20/ 0.33 mm ^{*(2)}											
Auto-focused color camera with 5M resolution, Working distance 100 mm ~ ∞											
Support Maximum 2× GigE 2D cameras or 1× GigE 2D Camera + 1× 3D Camera ^{*(3)}											
Force Sensing ^{*(4)} Optional		Force Sensing Standard		Force Sensing ^{*(4)} Optional		Force Sensing Standard		Force Sensing ^{*(4)} Optional		Force Sensing Standard	
+/- 300 N		+/- 300 N		+/- 300 N		+/- 300 N		+/- 300 N		+/- 300 N	
2 % F.S.		2 % F.S.		2 % F.S.		2 % F.S.		2 % F.S.		2 % F.S.	
5.5 % F.S.		5.5 % F.S.		5.5 % F.S.		5.5 % F.S.		5.5 % F.S.		5.5 % F.S.	
+/- 30 Nm		+/- 30 Nm		+/- 30 Nm		+/- 30 Nm		+/- 30 Nm		+/- 30 Nm	
0.3 % F.S.		0.3 % F.S.		0.3 % F.S.		0.3 % F.S.		0.3 % F.S.		0.3 % F.S.	
5 % F.S.		5 % F.S.		5 % F.S.		5 % F.S.		5 % F.S.		5 % F.S.	
^{*(1)} Please contact sales/agent for detailed specifications.											
^{*(2)} The data in this table are measured by TM laboratory and the working distance is 100mm. It should be noted that in practical applications, the relevant values may be different due to factors such as the on-site ambient light source, object characteristics, and vision programming methods that will affect the change in accuracy.											
^{*(3)} Refer to the official website of TM Plug&Play for camera models compatible to TM Robot.											
^{*(4)} Optional on others and total weight will increase by 500g.											

Specification											
TM12	TM14	TM16	TM20	TM12M	TM14M	TM16M	TM20M	TM12X	TM14X	TM16X	TM20X
32.8kg	32.5kg	32kg	32.8kg	32.8kg	32.5kg	32kg	32.8kg	32.5kg	32.2kg	31.7kg	32.5kg
12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg	12kg	14kg	16kg	20kg
1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mm	1300mm	1100mm	917mm	1300mm
+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 270°	+/- 360°	+/- 360°	+/- 360°	+/- 360°
+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 180°	+/- 360°	+/- 360°	+/- 360°	+/- 360°
+/- 166°	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163°	+/- 155°	+/- 166°	+/- 166°	+/- 163°	+/- 155°	+/- 166°
120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s	120°/s	120°/s	120°/s	90°/s
180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s	180°/s	180°/s	180°/s	120°/s
180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s	180°/s	150°/s
180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s	180°/s	150°/s	180°/s	180°/s
180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s	180°/s	180°/s	180°/s	225°/s
4m/s											
+/- 0.1mm											
6 rotating joints											
Digital In: 16 / Digital Out: 16											
Analog In: 2 / Analog Out: 1											
Digital In: 4 / Digital Out: 4											
Analog In: 1 / Analog Out: 0											
24V 2.0A for control box, 24V 1.5A for tool											
IP54 (Robot Arm) IP32 (Control Box)											
300 W											
0-50°C											
ISO Class 3											
100-240 VAC, 50-60 Hz				22-60 VDC			24-60 VDC	100-240 VAC, 50-60 Hz			
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